

# Simulator of magnetometer and gradiometer to evaluate detection and classification algorithms



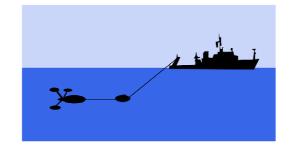
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## **Objective:**

develop a simulator of the output of a magnetometer or magnetic gradiometer towed behind a ship in the vicinity of a metal object, from survey to map generation

## **Motivation:**

- · compare different sensor and survey configurations
- · assess detection/classification algorithms in controlled conditions



## Simulator features:

- Model targets by magnetic dipoles
- Model sensors that provides intensity of the total magnetic field (target field plus Earth's magnetic field) at sensor location
- Model errors in the estimation of the position and orientation of the sensor
- Display total field, target field, anomaly field (projection of target field on Earth's magnetic field)
- Model magnetometers and several gradiometer configurations (two or three magnetometers)
- Include recovery of vertical gradient and upward continuation from two magnetometers

# Example of use #1: comparing sensor configuration: What do you lose by using two magnetometers instead of three?

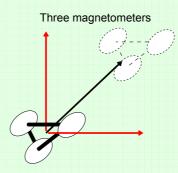
**Method:** is it possible to recover the vertical gradient with only two magnetometers?

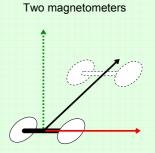
With three magnetometers, vertical gradient from difference of sensor measurements

**With two magnetometers**, horizontal gradient from filtering of horizontal data (e.g. in Fourier space)

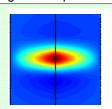
## Conclusions:

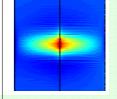
- Recovering the vertical gradient is theoretically possible by filtering in the Fourier space
- Sensitive to re-sampling of sparse data collected during survey





Magnetic maps over a target (with trajectory)





Elongated shape due to poor data sampling

Artifacts due to re-sampling of sparse data before filtering

# Example of use #2: Algorithm evaluation

Method: Compare performance of different detection and classification algorithms based on the same controlled conditions

## **Future work:**

- State-of-art-the interface
- Improved model of position and orientation errors
- More re-sampling algorithms



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